

STScI | SPACE TELESCOPE SCIENCE INSTITUTE

EXPANDING THE FRONTIERS OF SPACE ASTRONOMY

Moving Targets Level 2

Blair Porterfield, Weston Eck, John Stansberry, and Bryan Holler JWST Master Class

November 2019

Where to get help

) Where to go for help

JWST Documentation on Moving Targets (JDox)

Can be found at <u>JWST Moving Target Observations</u>

Context Sensitive Help in the APT

Hovering the cursor over the parameters in the form editor will display a question mark. When clicked on it will bring up the relevant section of JDox.

Context Sensitive Help in the ETC

Blue question mark icons are present throughout the web application. When clicked they will bring up the relevant section of JDox.

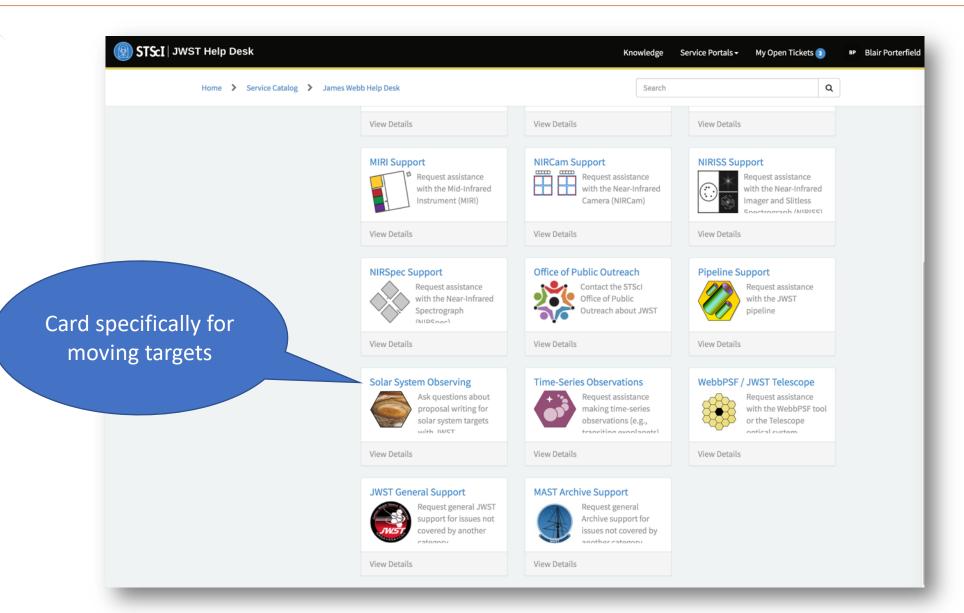
JWST Help Desk

Can be found at <u>https://stsci.service-now.com/jwst</u>

Requires a MyST account to submit questions (as does submitting a proposal)

Can search the knowledge database without an account

Where to go for help



Moving Target Visibility Tool (MTVT)



The MTVT is a command line tool used to determine the time periods when a target of interest is in the JWST field of regard (FOR). It is a wrapper to the General Target Visibility Tool (GTVT).

The MTVT was originally developed by Mike Kelley. Mees Fix is responsible for ongoing development and maintenance of the tool.

The MTVT comes as part of a package with the General Target Visibility Tool

Installation and usage

One can download a .zip file or clone the repository for GTVT from the following GitHub link:

https://github.com/spacetelescope/jwst_gtvt

and install the tool inside the resulting "jwst_gtvt-master" directory (you should see a file called "setup.py" in this directory) with the command

python setup.py install

Alternatively, if you are familiar with "pip", you can install the tool directly with

pip install git+https://github.com/spacetelescope/jwst gtvt.git

Python package dependency: astroquery

conda install astroquery

Alternatively, if you are familiar with "pip", you can install the package with the following command:

pip install astroquery



(GTVT)

MTVT: Documentation

Home / Other Tools / Target Visibility Tools / JWST General Target Visibility Tool Help

JWST General Target Visibility Tool Help



The JWST General Target Visibility Tool (GTVT) is a command-line Python tool that provides quick-look assessments of target visibilities and position angles for all JWST instruments.

General Target Visibility Tool Help

Home / Other Tools / Target Visibility Tools / JWST Moving Target Visibility Tool Help

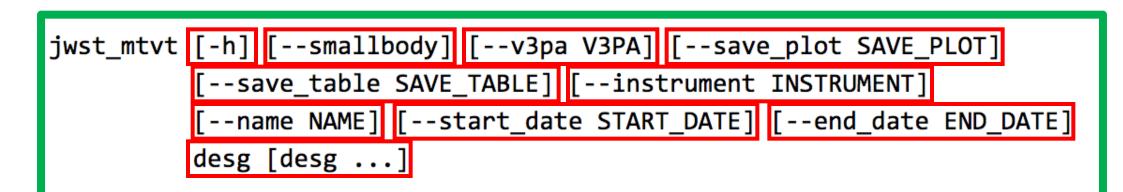
JWST Moving Target Visibility Tool Help



The JWST Moving Target Visibility Tool (MTVT) is a command-line Python tool that provides quick-look assessments of moving target visibilities and position angles for all JWST instruments.

Moving Target Visibility Tool Help





Only required argument: Target name or number

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- Visibility of a planet
- Visibility of a satellite
- Visibility of an asteroid/NEA/Trojan/Centaur/KBO
- Visibility of a comet
- Visibility of an interstellar object

Moving Target Visibility Tool (MTVT): On-line Resources

JDox:

- JWST Field of Regard: JWST Observatory Coordinate System and Field of Regard
- JWST Orbit: JWST Orbit
- GTVT: General Target Visibility Tool Help
- MTVT: Moving Target Visibility Tool Help

Other links:

- JPL/Horizons: <u>https://ssd.jpl.nasa.gov/horizons.cgi</u>
- Astroconda: <u>https://astroconda.readthedocs.io/en/latest/</u>
- Astroquery: https://astroquery.readthedocs.io/en/latest/

Exposure Time Calculator (ETC)



There are currently no unique features for moving targets in the JWST ETC.

ETC: Useful Features for Moving Targets

Example Science Program and Sample Workbook

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Home / Near Infrared Spectrograph / NIRSpec Example Programs / NIRSpec IFU and Fixed Slit Observations of Near-Earth Asteroids of Near-Earth Asteroids

Example Science Program #34

This example science program presents an application of the Moving Target Roadmap, using NIRSpec IFU observations of Near-Earth Asteroids as an example. This article covers selection of fast moving targets and appropriate observing modes based on the targets' positional uncertainties. Proper determination of exposure parameters in the ETC and construction of an APT file are covered in separate linked articles.

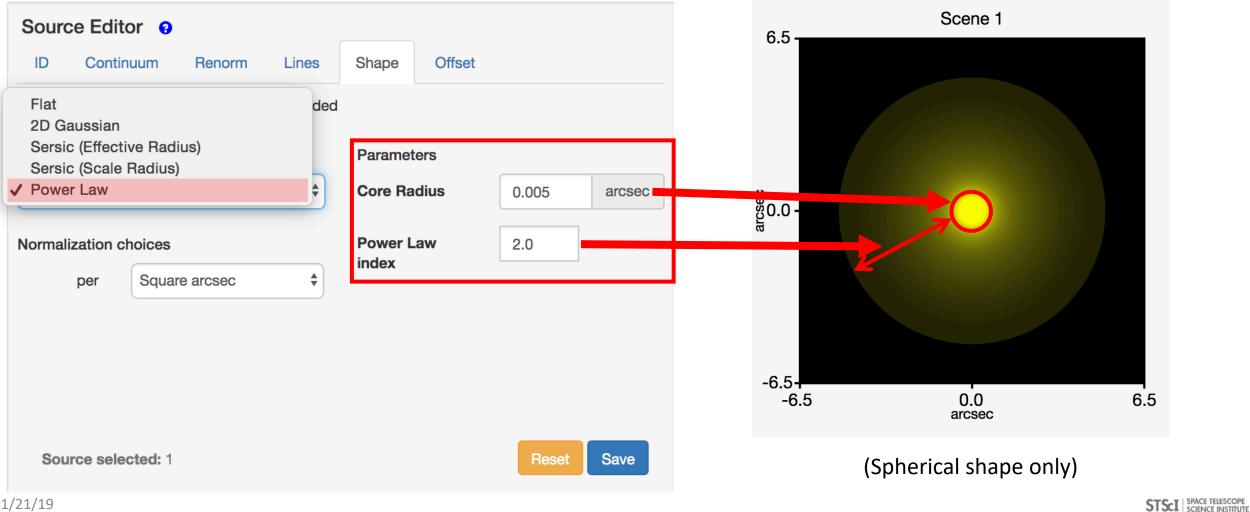
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		#33: NIRISS WFSS and NIRCam Imaging of Galaxies Within Lensing Clusters
		#34: NIRSpec IFU and Fixed Slit Observations of Near-Earth Asteroids

https://jwst-

docs.stsci.edu/near-infraredspectrograph/nirspecexample-programs/nirspecifu-and-fixed-slitobservations-of-near-earthasteroids

ETC: Useful Features for Moving Targets

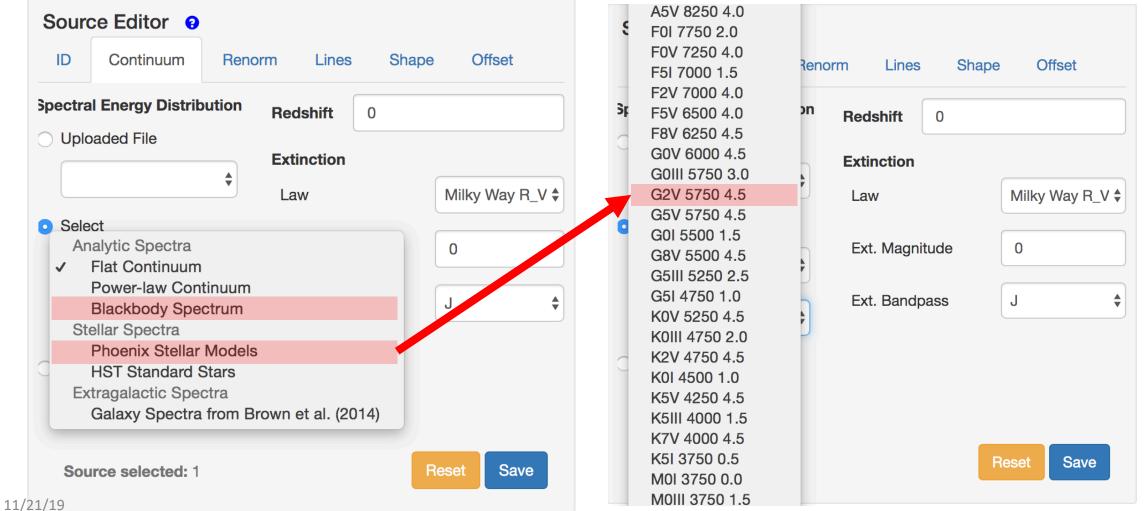
Power-law flux distribution



11/21/19

ETC: Useful Features for Moving Targets

Template spectra: G2V Phoenix stellar model & Blackbody



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- Understand the workaround for modeling the flux from a giant planet
- Model scattered light from a giant planet for observations of a satellite

• Model a comet



- JWST ETC web application: <u>https://jwst.etc.stsci.edu/</u>
- JWST ETC documentation: Exposure Time Calculator Overview
- Pandeia engine documentation: JWST ETC Pandeia Engine Tutorial
- Moving targets in the ETC: JWST Moving Targets in ETC

Specifying Moving Targets

New Moving Target

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Moving Target Template

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Level 1 refers to a target in orbit about the Sun.

• Planets, Asteroids, and Comets.

Level 2 refers to a target whose motion is normally described with respect to a Level 1 object.

• Planetary Satellites, Surface features on Planets, offsets from Asteroid or Comet.

Level 3 refers to a target whose motion is normally described with respect to a Level 2 object.

• Surface feature on planetary satellites, Pointing offset from planetary satellite.

Moving Target Template: Io

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Moving Target Template: Io

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Moving Target Templates: Io

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Moving Target Templates: Io

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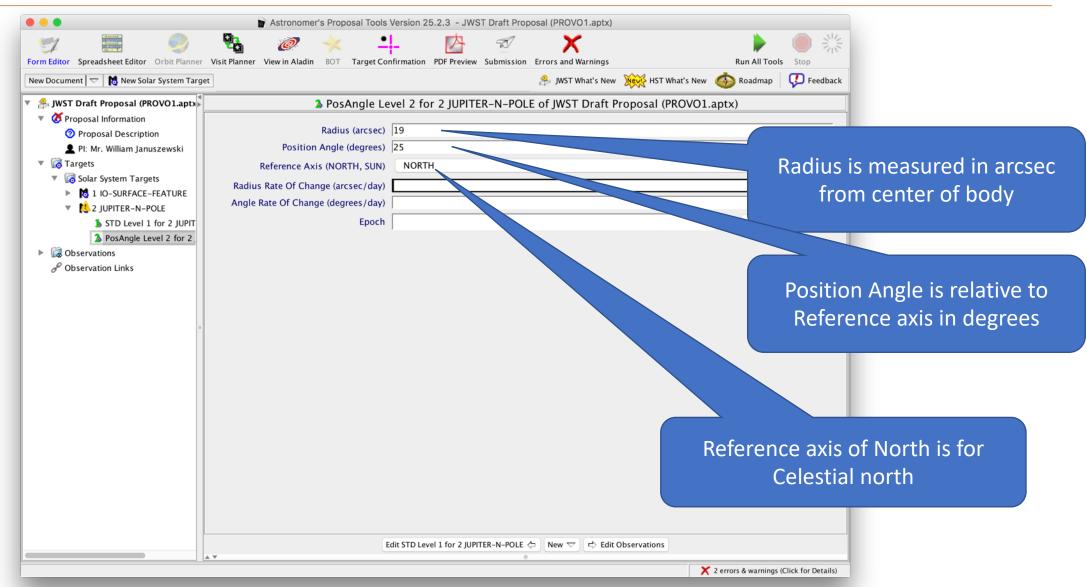
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Moving Target Template: Jupiter N Pole

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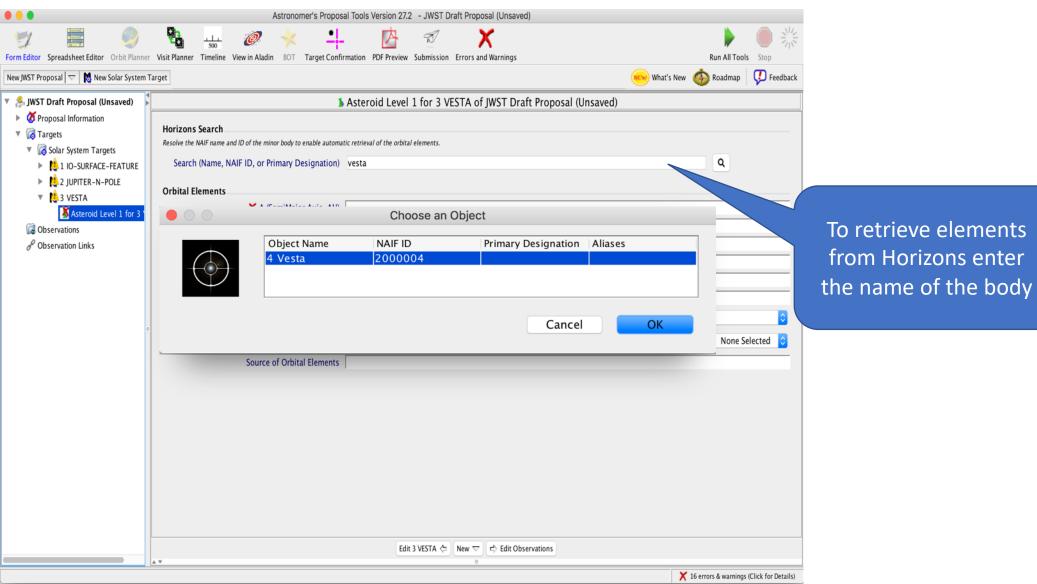
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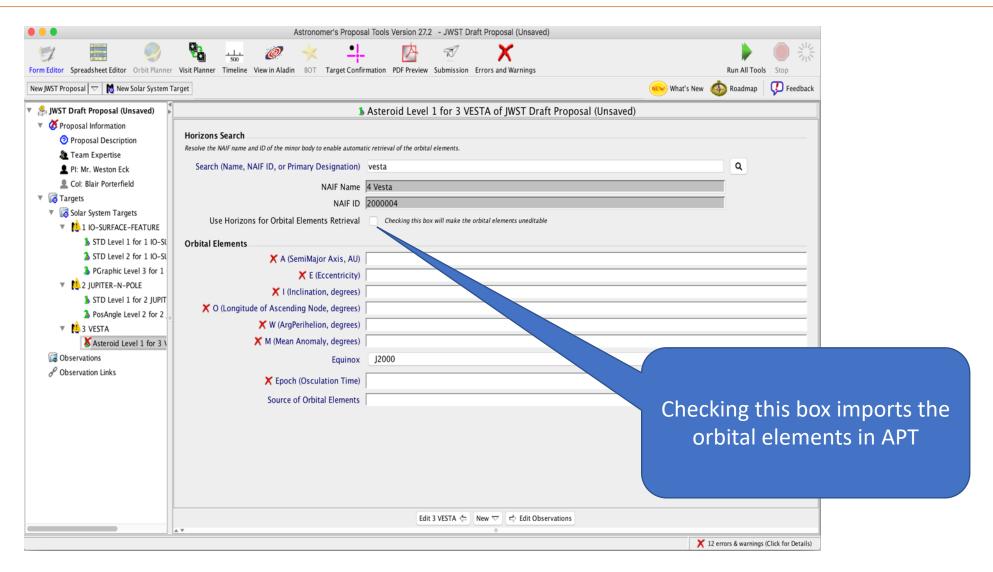
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Horizons Interface



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v	STD Level 1 for 2 JUPIT PosAngle Level 2	Date Retrieved 2019 A (SemiMajor Axis, AU) 2.36 E (Eccentricity) 0.08 I (Inclination, degrees) 7.13	61017006168899 8940671368300425	
		O (Longitude of Ascending Node, degrees) 103. W (ArgPerihelion, degrees) 150. M (Mean Anomaly, degrees) 356.	3.9831114166946 0.0028930287553	
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	🔻 🐼 Proposal Information		
	Proposal Description	Horizons Search Resolve the NAIF name and ID of the minor body to enable automatic retrieval of the orbital elements.	
	🎘 Team Expertise		
	PI: Mr. Weston Eck	Search (Name, NAIF ID, or Primary Designation) Vesta	۹
	L Col: Blair Porterfield	NAIF Name 4 Vesta	
	▼ 🐻 Targets	NAIF ID 2000004	
	 Golar System Targets 1 IO-SURFACE-FEATURE 	Use Horizons for Orbital Elements Retrieval 🧹 Checking this box will make the orbital elements uneditable	
	🖒 STD Level 1 for 1 IO-Sl	Orbital Elements From Horizons	
	🔈 STD Level 2 for 1 IO-Sl	Click the "Update Orbital Elements From June 5 button to request the latest orbital elements from Horizons.	
	3 PGraphic Level 3 for 1	Update Orbitations From Horizons	
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	🔻 🚑 JWST Draft Proposal (PROVO1.apt)	Observation 1 of JWST Draft Proposal (PROVO1.aptx)	
	 Ø Proposal Information Targets 	Number 1 Status: UNKNOWN Duplication	
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	 2 JUPITER-N-POLE 3 SEDNA 	Template NIRCam Imaging	
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STScI | SPACE TELESCOPE SCIENCE INSTITUTE



Solar System Special Requirements are a powerful tool for defining what conditions are occurring for optimal science return

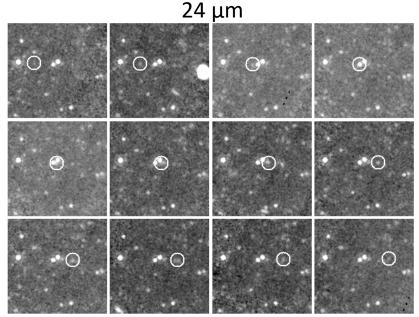
Just don't get carried away.

Use the windows you need to meet your science goals but keep in mind that each requirement restricts scheduling windows.



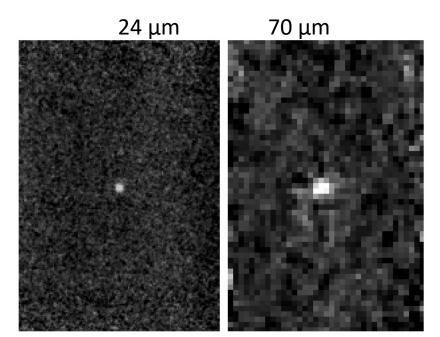
This strategy combines 2 or more observations of a target, taken close together in time, to remove most of the background objects from the data.

- This results in improved SNR for observations of targets that are comparable to the brightness of typical background objects (or fainter!).
- Many measurements made with *Spitzer* and *Herschel* would not have been possible had they not implemented moving follow-on constraints.



26308 (1998 SM165) - Spitzer

- 1) Co-add in sky coordinates
- 2) Subtract Sky from individual images
- 3) Coadd result in co-moving frame



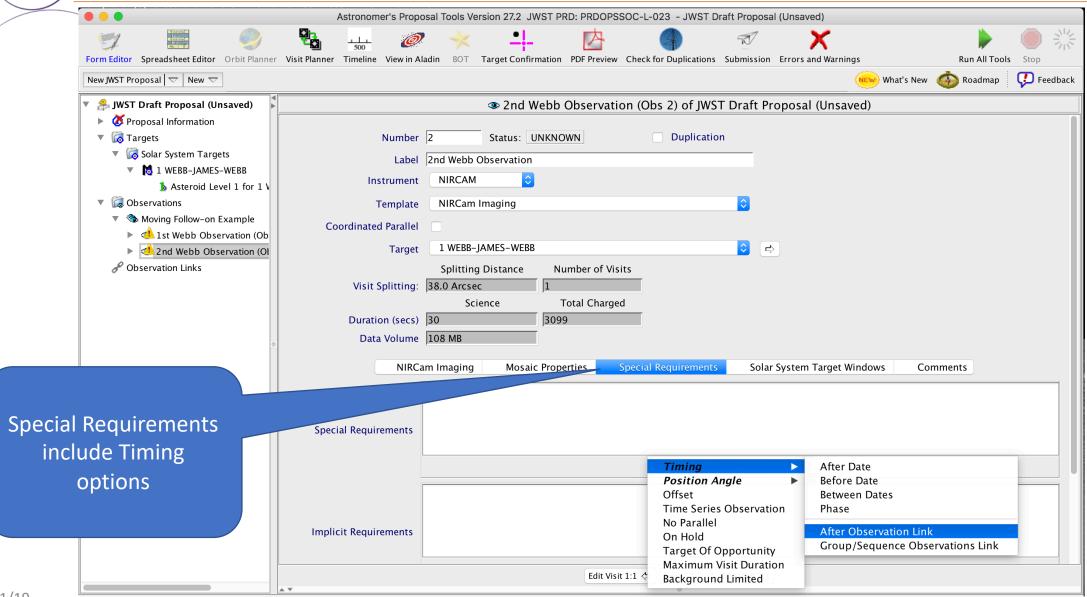
For moving follow-on to work requires:

- 1. Target moves a significant distance relative to the PSF size (well-separated target observations).
- 2. Target moves significantly less than ½ of the FOV of the individual observations.

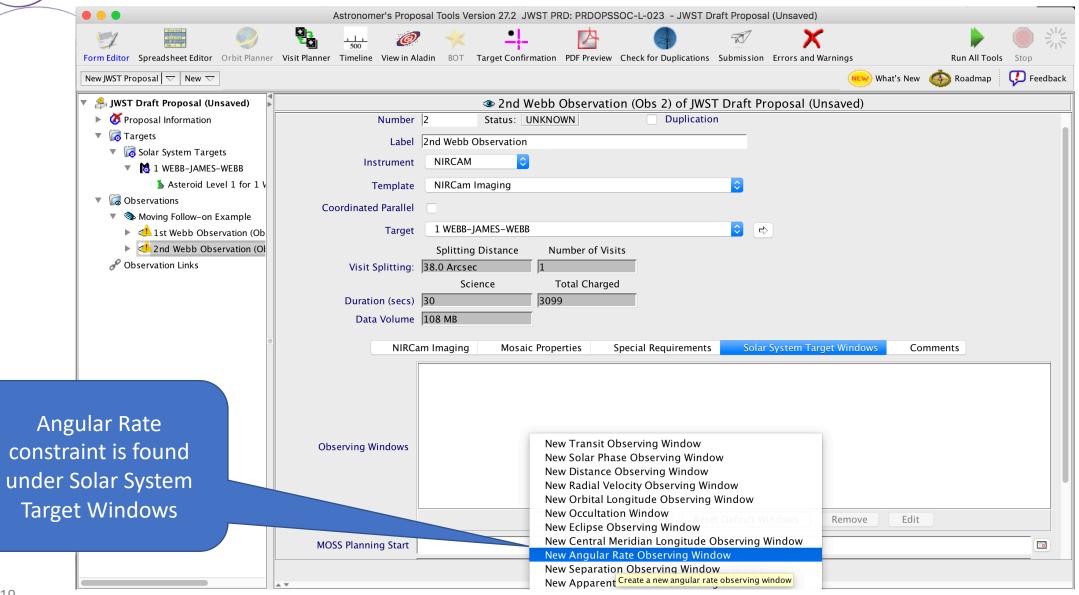
APT Implementation:

- 1. Create 2 observations of the target.
- 2. Create a Special Requirement on the 2nd observation: *Timing -> After Observation* link.
 - Based on the apparent rate of motion (d"/dt) of the target, set the Min and Max Interval:
 - 1. Min: d"/dt * Min > N * FWHM (where N > 3)
 - 2. Max: d"/dt * Max < FOV_size * Frac (where Frac < 0.3)
- 3. If the apparent rate of motion varies significantly during the observing window, create a *Solar System Target -> Angular Rate Observing Window* on one observation.
 - 1. You will have to choose to constrain the angular rate to be > or < your preferred rate.
 - 2. Choose a limiting rate that satisfies the After Observation conditions above while providing maximum scheduling flexibility.
- 4. Check your results in Visit Planner!!



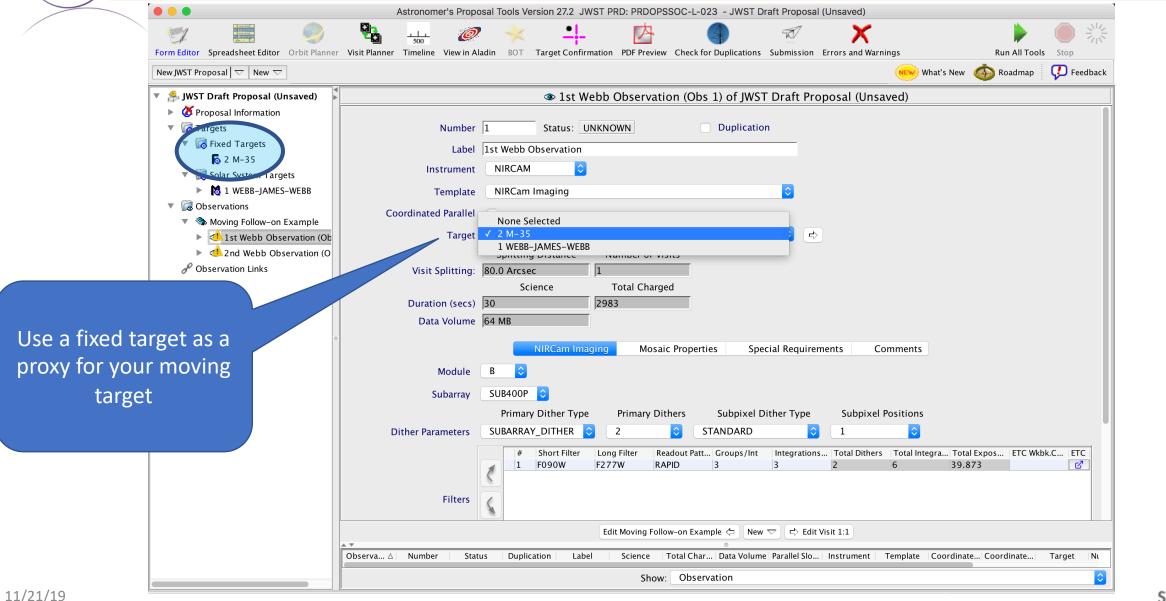


	Astronomer's Proposal Tools Version 27.2 JWST PRD: PRDOPSSOC-L-023 - JWST Draft Proposal (Unsaved)
Form Editor Spreadsheet Editor Orbit Planner	Visit Planner Timeline View in Aladin BOT Target Confirmation PDF Preview Check for Duplications Submission Errors and Warnings
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	After Observation Link
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specifies observation	After observation 1st Webb Observation (Obs 1)
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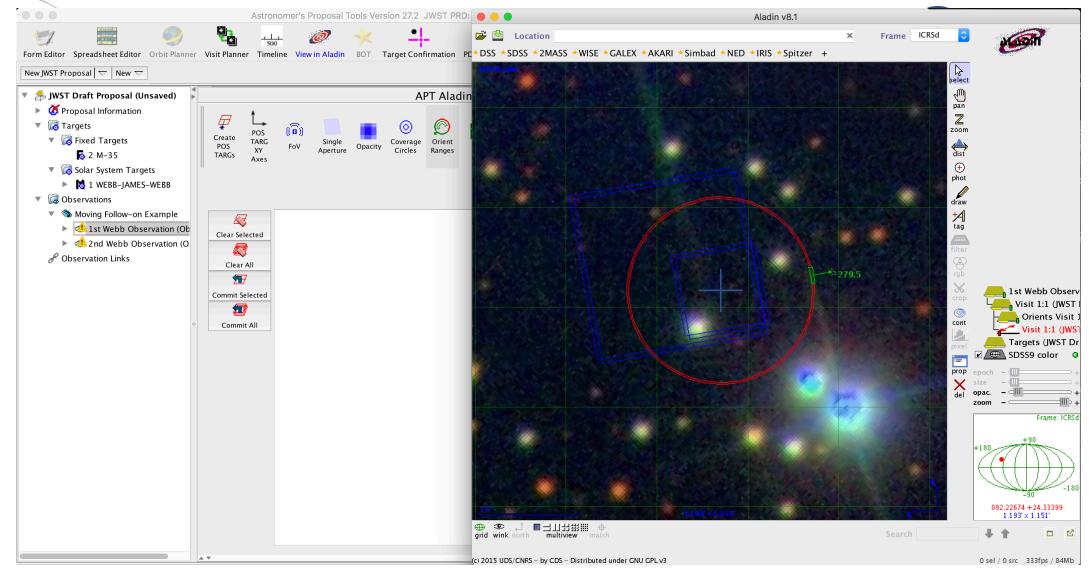


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Visualization: Moving Target Proxy



Moving Target Visualization: Proxy Fixed Target



APT Moving Targets: On-line JDox Resources

- Moving targets in APT: Moving Targets in APT
- APT Solar System Target Windows: Solar System Special Requirements
- Visualizing Moving Target Observations: <u>Tutorial on Visualizing Dithers of a Solar System</u> <u>Observation in APT</u>
- APT Special Requirements: <u>APT Special Requirements</u>
- ETC to APT interface: ETC to APT Interface Support Information
- APT Visit Planner: <u>APR Visit Planner</u>
- General APT documentation: <u>Astronomers Proposal Tool Overview</u>